

Task Data

-a. Date :	24/07/2010 AM	-f. Next Briefing :	06:45 at CLP
-b. Sunrise / Sunset :	06:30/21:40	-g. Observer :	Pilot's choice
-c. PZs in force :	All	-h. Solo flight :	No
-d. Launch Area :	Pilot's choice	-i. Search Period :	4h AM / 3h PM
-e. Launch Period :	06:45 / 07:40		

Task 3	R15.1 Pilot Declared Goal
a. Marker colour :	Green
b. Task / Markers order :	Any
c. Dropping method :	FREE R12.10
d. Marker Measuring Area :	1000m
e. Scoring period / Scoring area :	Until 09:00 AM / -
f. Task data R15.1	
a. Declaration time and place	On observer's report sheet before take-off
b. Number of goals permitted	1
c. Goals available for declarations	-
d. Dist Min/Max	1km / 11km

Task 4	R15.4 Fly In
a. Marker colour :	Red
b. Task / Markers order :	Any
c. Dropping method :	GRAVITY R12.9
d. Marker Measuring Area :	1000m
e. Scoring period / Scoring area :	Until 09:00 AM / -
f. Task data R15.4	
a. Position of set goal or target	2614/7020
b. Dist min/max	4km / Limits of the map
c. Number of take-offs	1

Task 5	R15.2 Judge Declared Goal
a. Marker colour :	Blue
b. Task / Markers order :	-
c. Dropping method :	GRAVITY R12.9
d. Marker Measuring Area :	1000m
e. Scoring period / Scoring area :	Until 09:00 AM / -
f. Task data R15.2	
a. Position of set goal/target	2632/6512

Task 6	R15.12 Land Run
a. Marker colour :	-
b. Task / Markers order :	-
c. Dropping method :	-
d. Marker Measuring Area :	-
e. Scoring period	Until 09:00 AM
f. Task data R15.12	
a. Description of point A,B,C	See description below
b. Description of scoring area(s)	See description below

The LRN scoring area is an area with a radius of 4km around 2700/5900. Point A is the first trackpoint when entering the area and point C is the first trackpoint when leaving the area. Point B is the trackpoint giving the greatest triangle (2D projection) in the scoring area.

L'aire de marquage du triangle est définie par un rayon de 4km autour du point 2700/5900. Le point A est le premier point GPS dans l'aire et le point C le premier point GPS à l'extérieur de l'aire. Le point B est le point GPS donnant le plus grand triangle (Projection 2D) dans l'aire de marquage.

